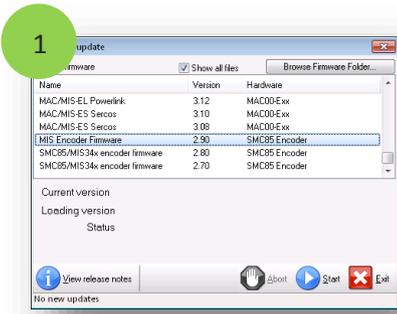
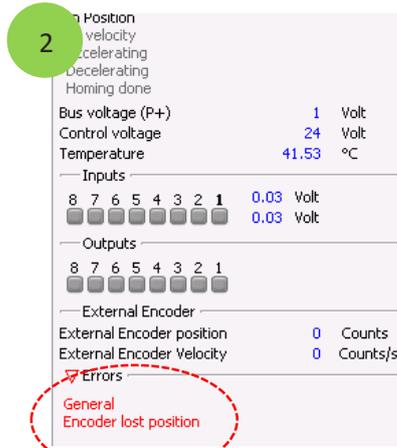


# MIS/MIL 17/23/34/43 – H3/H4 encoder firmware update

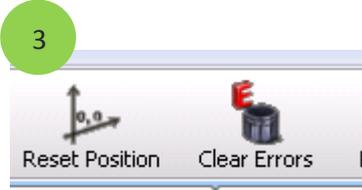
This quick guide explains how to firmware update the encoder and perform the calibration afterwards.



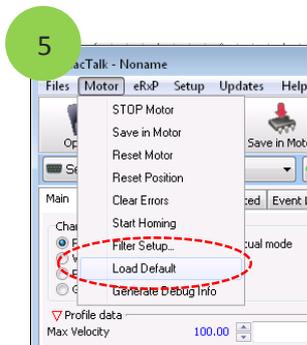
Update the encoder.



The "Encoder lost position" appears.



Click "Reset Position", then "Clear Errors". The errors should now disappear.



"Load Default" settings in the motor before the calibration.



Unmount any mechanical load from the shaft because the motor must be able to move freely.



Type 999 in the Command field and press 'Enter'  
Then 350 and press 'Enter'



Wait ~2.5 minutes for the calibration to complete.



When the motor stands still, the Position 1 register holds the value 64 (click on the blue number to update).